

## EM-483 Specifications

by [Tumbleweed](#) on September 1, 2015

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## Intro: EM-483 Specifications

I have seen many people, including myself looking for technical specification for this particular stepper motor stripped from old printers but nothing seems to show up so I decided to share with you some characteristics and the recommended operating parameters I have discovered:

Type: Bipolar Stepper Motor

Supply: 5V

Coil Resistance: ~3.6 omhs

Max Current: ~1.4A

Operating frequency: 500Hz

Maximum speed: 150 rot/min



## Step 1: Driving algorithm for the stepper motor

I have set the operating frequency at 500Hz because if you go higher the electromagnetic inertia of the of the coils will make it so there is a high danger for the motor to skip steps if put under load. It also gives you nice round numbers when doing the math.

As shown in the picture the algorithm requires the following 8 step sequence applied to both coils for it to work properly. Each sequence takes 8ms and moves the motor 4 steps (7.2 degrees).

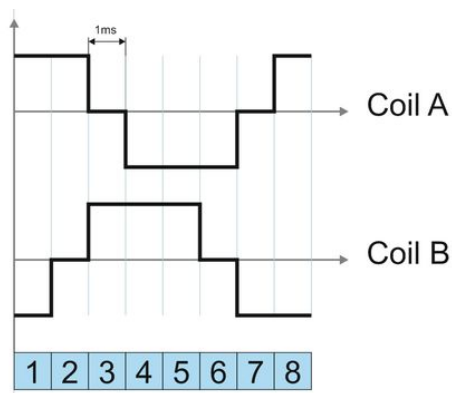
Because the stepper motor has 1.8 degree step it takes 200 steps to make a full rotation, thus we can calculate that a full rotation will be done in 400ms.

And from that you can get the 150rot/min maximum speed.

The 500Hz operating frequency is derived from the fact that you have 4ms pulses for each step (3ms active 1ms pause) but you have 2 coils, so you get a step each 2ms.

$$1000\text{ms}/2\text{ms}=500\text{Hz}$$

Correct me if I'm wrong.



## Related Instructables



**Arduino Stepper Motors** by cornelam



**Make a super cheap 3D printer using recycled parts** by Practical Techonlogy



**Intro to Stepper Motors** by Aleator777



**How to use a Stepper Motor** by JColvin91



**Stepper Motor Easy Driver** by williebme



**Drive a Stepper Motor with an AVR Microprocessor** by The Real Elliot

## Comments

1 comments

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**amberrayh** says:

This is very helpful. Thank you for sharing!

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